INVESTIGATING THE PERFORMANCE VALUES OF SILICON-CARBIDE TECHNOLOGY

- Can Sustain up to 10X higher voltages than Si
- Can carry almost 5X more current than
 Si
- Higher temperature tolerance than Si
- Up to 3X higher thermal conductivity
 than Si
- Can switch up to 10X faster than Si



EXPERIMENTATION OF JOBY MOTOR CONTROL

- Troy T. Kuhns
- Victor Valley College
- Sophomore
- Mechanical Engineering
- Yohan Lin & Kurt Kloesel
- Rt Vehicle Integration and Test
- H.E.I.S.T. Project
- Welder/Fabricator



CREE 6-CHANNEL GATE DRIVER AND SILICON CARBIDE SIX-PACK

- This is the board that we would experimentally test to investigate its possibility of controlling the JOBY motor.
- Capable of creating 3-phase power.
- A/C TO D/C POWER CONVERSION
- OUPUT OF 900VDC
- BIG BOARD WITH LOTS OF COMPONENTS
- ALSO EXPENSIVE WITH THREE-PHASE MODULE ATTACHED
- INSTEAD OF EXPERIMENTING WITH THIS.......





LEARNING TO CONTROL AND UNDERSTAND SIC MOSFET GATE DRIVER

- Single gate driver = smaller compact simpler design, as compared to six-channel, = cheaper price point if, and we did, burn it up.
- New to circuit board function testing and understanding.
- Good insight on output values with respect to input values
- Great for developing a working knowledge of individual components like the gate and optoisolator.





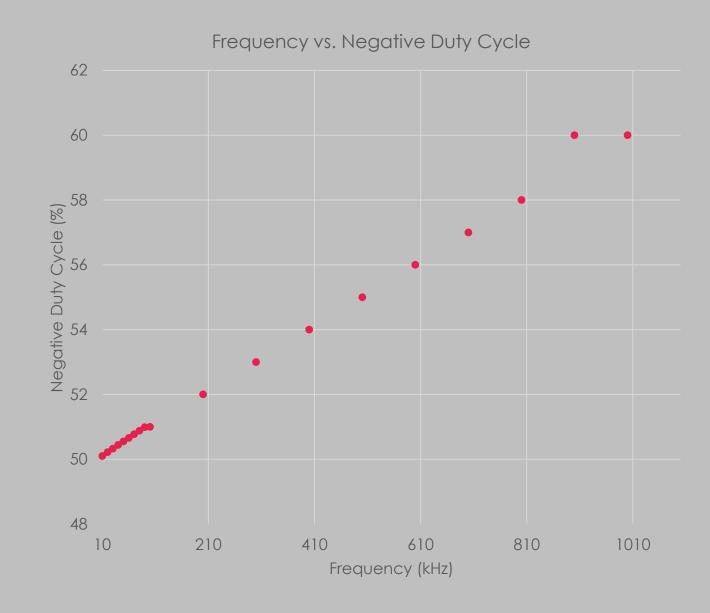
TESTING SETUP OF THE CREE CRD-001

- Two different power sources to control the high and low input voltages.
- Signal generator used to control input square wave through amplitude, frequency and voltage.
- Recording data on the oscilloscope,
 looking predominately at duty cycle.

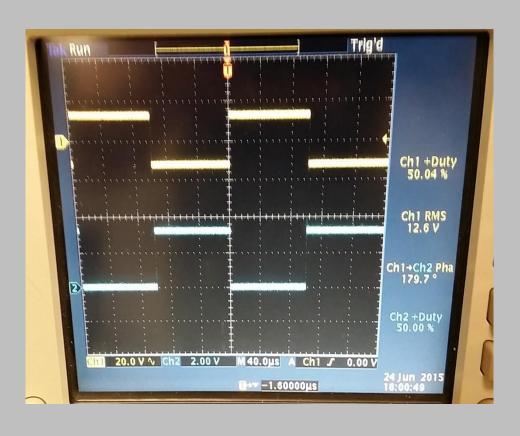


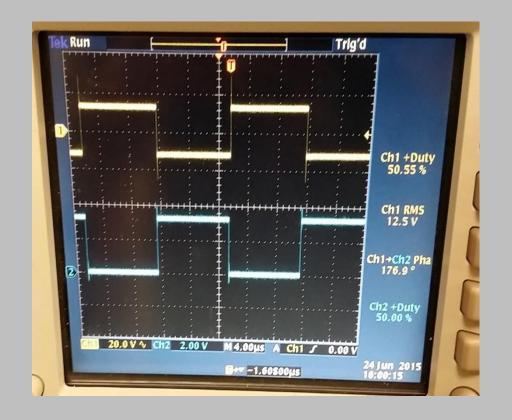
DUTY CYCLE PERFORMANCE WITH INCREASING FREQUENCY

- Cree CRD-001 SiC MOSFET Gate Driver
- VCC High 10.0 Volts
- VCC Low 10.0 Volts
- Signal Generator Amplitude 5Vrms
- Offset 0 Volts
- +1% (-) Duty Cycle Change per 100 (kHz)
- -0.1V RMS for every +200kHz up to 1Mhz
- Signal Failure at 3.11MHz



FREQUENCY V.S. DUTY CYCLE

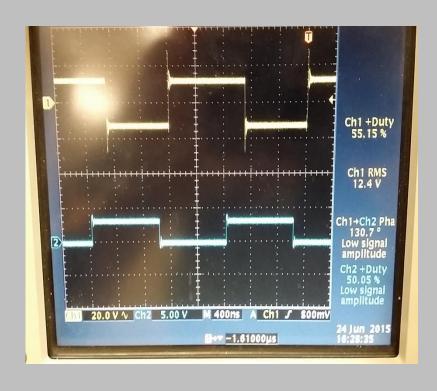


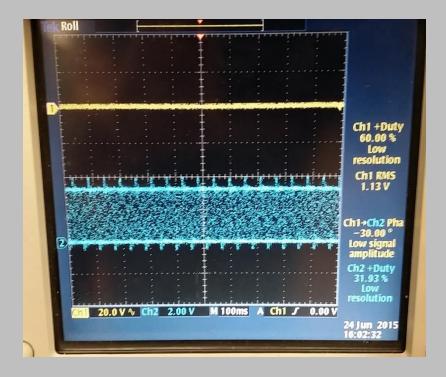


5 KHZ

50 KHZ

FREQUENCY V.S. DUTY CYCLE



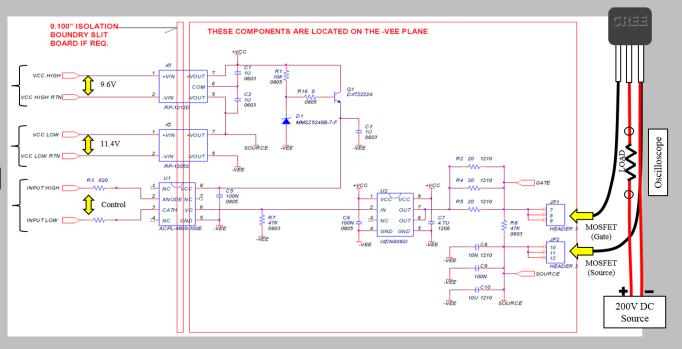


500 KHZ

5 MHZ

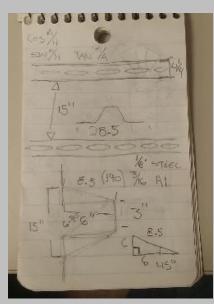
CREE CRD-001 WITH CREE C2M0025120D MOSFET

- Using the Cree CRD-001 to power the Cree mosfet to test and record the performance values.
- Using two power supplies, the first with two separate channels to control the high and low voltage input for the board and the second to power the mosfet on.
- Signal generator to create the square wave and oscilloscope to record output values.
- Load bank for the drain leg of the mosfet.













- Repurposing an old server rack unit to fabricate a safety test enclosure for the JOBY motor and propeller to be used for testing the SiC driver board.
- Initial design drawings of the motor mount.
- Motor mount made from 6061 T-6 Aluminum cut out with a water jet and bent to shape with hydraulic press. Keeping the center of mass located along the X and Y axis of the enclosure.









- When inquiring about torque specs for propeller bolts I noticed this bushing. To equally distribute the bolt head pressure on the propeller I had created a bolt head pressure distribution washer.
- Started off with a solid 3" piece of 6061 T-6 Aluminum round stock.
- On the lathe we turned it down to a O.D. of 2.165" and using a center bore cutting in an I.D of 1.215".
- Using the mill to find centricity we plotted and drilled the hole pattern.
- Finally taking our piece back to the lathe we cut out 3 different washers of varying thicknesses.





Left Side: Motor test cage enclosed 3/5 of the way with expanded metal. For easy access to front and back of test motor I used 1/4 quick turn cam locks.

Right Side: An Aluminum frame housing a phenolic block to electrically isolate each motor terminal lug. Lugs on both sides allow for quick connect/disconnect with out removal of rear panel.











- A few pictures of the completed motor stand with front panel attached and removed.
- Using a piece of sheet metal on the bottom of test cage to act as an active ballast support system.

MOUNTING TI CONTROLLER BOARD TO TEST ENCLOSURE

- Using a Texas Instruments DRV 8301 motor controller board we could gather some initial data.
- Mounted the board to a rack shelf and mounted the shelf to the top of the motor cage.
- Inline fuses to thermally and electrically protect the board from to much current.



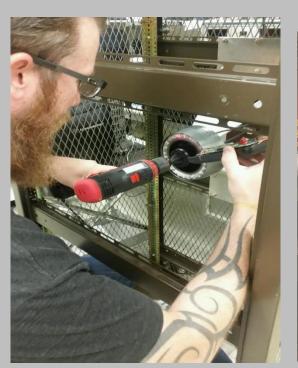


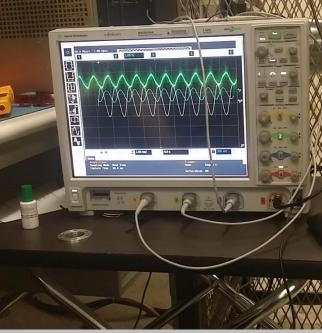


JOBY MOTOR IN ACTION WITH SIGNAL OUTPUT









- Controlling the JOBY motor with micro-controller and manual methods for data capture and analysis.
- Using a chuckable 3-D printed motor adaptor, cordless drill, and tachometer to compare RPM to Voltage variables.

CAPSTONE WIRING PROJECT

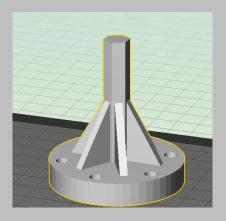








OTHER PROJECT TASKS I WAS **INVOLVED WITH**

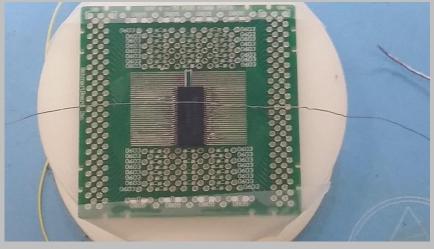


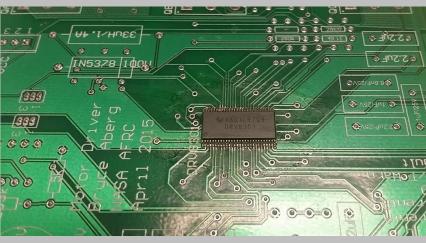












BACK TO THE SILICON-CARBIDE

- Connected a 3-Phase load to the CREE board.
- Tested and triggered individual transistors.
- The Texas Instruments 28335
 Delphino micro-controller has a 3.3V output.
- The CREE board needs 5V per channel to switch on.
- Set up a series of 5V op-amps in between to help power board.



ACKNOWLEDGMENTS

- Becky Flick
- The Aero Institute
- NSF Crest Grant #1345163
- Yohan Lin & Kurt Kloesel
- Michael Butros & Khalid Rubayi
- Jim Murray
- Bob Novy, Brent Bieber, Dennis Pitts
- Ed Swan, Andy Blua, Daryl Lott, Keith Day, Don Whitfield, Eric Nisbet, Kyle Whitfield, Bill Stanfield, Jerry Cousins, Jason Preece, Andy Ohmit, Rick Pokorski, Jeff Requist

